





Axial piston variable pump

Used for hydraulic drives in open loop circuits

Features:

- Swashplate axial piston pump.
- · Adjust the angle of swashplate to realize the stepless variable.
- Good suction characteristic.
- Have the structural design of compact, light weight, low noise characteristics.
- The sensitivity of control system.
- Flow is proportional to the drivek speed and to the displacement.
- Nominal pressure reach to 35 Mpa.
- · Long service life, high-precision bearings.
- · Hydrostatic balance slipper, improve the life of pump.
- With swashplate angle indicator.

EPrun

* Ordering Code

P	-		A4VS	0			/			-					
Prun Hydraulic		Hydraulic fluid	Axial piston unit	Type of operation	Size	Mode of operation		Series	Direction of rotation		Seals	Shaft end	Mounting flange	Service ports	Through drive

* Model Description

HF: HFB and HFC-Mediums

Prun Hydraulic	Р
Hydraulic fluid	
Mineral oils	

Axial piston unit

ı	Variable displacement pump, industrial uses	A4VS
-1	variable displacement pump, industrial uses	~~ v

Type of operation

Pump, open circuits	0
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Size

Displacement Vg max(ml/r)	40	71	125	180	250	355	500	
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Mode of operation

Pressure control DR	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	DR
Power control with Hyperbolic open, curve LR	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	\checkmark	LR
Manual control MA	\checkmark	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	MA
Electronic control EO	\checkmark	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	\checkmark	$\sqrt{}$	$\sqrt{}$	EO
Hydraulic control, pilot pressure dependent HD	\checkmark	√			√	V	√	HD

1002 1391 1976 2783

564

206

795

318

398

186

Series

$\sqrt{}$	$\sqrt{}$	_	_	_	$\sqrt{}$	_	10
_	_	\checkmark	\checkmark	$\sqrt{}$	$\sqrt{}$	\checkmark	22
_	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	30

Direction of rotation

Mish view on aboth and	Clockwise	R
With view on shaft end	Counterclockwise	L

Seals

NBR Nitrile rubber	Р
FKM Fluoro-rubber	V

Shaft end

Keyed parallel shaft	Р
Splined shaft	Z

Mounting flange	40	71	125	180	250	355	500	
ISO 4 hole	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	$\sqrt{}$	_	В

Service ports

Port B and port S 90 degree offset; auxiliary pressure port B1 Metric fixing screws	$\sqrt{}$	√	$\sqrt{}$	√	$\sqrt{}$	$\sqrt{}$	√	13
Port B and port S 90 degree offset; preesure connection B1 connected by flange	$\sqrt{}$	$\sqrt{}$	\checkmark	$\sqrt{}$	\checkmark	$\sqrt{}$	$\sqrt{}$	25

Through drive

Without auxiliary pump, without	1/	1/	1/	1/	1/	1/	1/	N00
through drive	V	V	V	V	· ·	V	V	1400

* Technical Data

Performance parameters(these figures did not consider the efficiency of mechanical and volumetric efficiency)

Size				71	125	180	250	355	500
Displacement (Vg max)		cm³/r	40	71	125	180	250	355	500
Max.speed (n ma	rpm	2600	2200	1800	1800	1500	1500	1320	
Max.Output	if n = n _{max}	L/min	104	156	225	324	375	532	600
flow	if n=1500rpm	L/min	60	107	186	270	375	532	-
May power	if n = n _{max}	KW	61	91	131	189	219	310	385
Max.power	if n=1500rpm	KW	35	62	109	158	219	310	_

223

64

40

395

113

54

696

199

87

N.m

N.m

kg

Parameter calculation

Weight(approximately)

Max.torque

Torque

Flow
$$q_v = \frac{V_g \cdot n \cdot \eta_v}{1000}$$
 [L/min]

Drive torque T =
$$\frac{1.59 \cdot V \cdot \triangle p}{1000 \cdot \eta_{mh}} [N.m]$$

 $(\Delta P=35MPa)$

 $(\Delta P=10MPa)$

 V_g = Geometry displacement each rotate [cm 3]

286

103

 $\triangle p$ = Pressuredrop/differential [bar

n = Rotary speed [rpm]

 η_v = Cubage's efficiency

Drive power P = $\frac{2\pi \cdot T \cdot n}{60000} = \frac{T \cdot n}{9549} = \frac{q_v \cdot \triangle p}{600 \cdot \eta_t} [kW]$ η_{mh} = Mechanical hydraulic efficiency $\eta_t = (\eta_t \cdot \eta_{mh})$ Overall efficiency

* Operation Mode

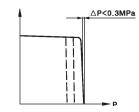
1. Outlined

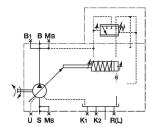
DR/DRG

Pressure control DR Remote pressure control DRG

Maximum pressure adjustment in

hydraulic system; Set range 20...350 bar; Option: remote control DRG



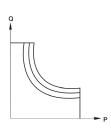


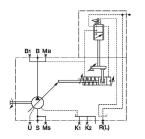


PA4VSC

LR Power control LR

The hyperbolic power control is kept constant at the same input speed Option: pressure control LR2D, remote control LR2G; Flow control LR2S, LR2F; Hydraulic stroke limiter LR2H; Mechanical stroke limiter LR2M; Hydraulic two point control LR2Z; Electrical discharge valve for help starting LR2Y.





FΟ

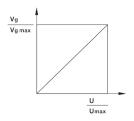
Hydraulic displacement control EO

Through the angel of the electronic feedback of the proportional valve to achieve stepless displacement adjustment.

Electronic control

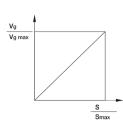
Available options: EO1K, EO2K

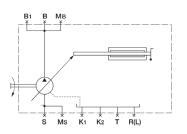
No valve EO1E, EO2E



Manual control MA

Stepless adjustment of flow through the hand wheel



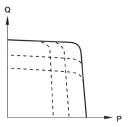


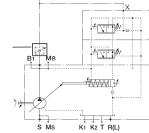
DFR

Pressure and flow control DFR

This control can be kept constant in the constant flow rate of the pump under the condition of constant change. Mechanical adjustable pressure control is preferred.

Available options: the throttle hole in the x of the oil port DFR1





Hydraulic control HD

Pump flow(displacement) of the stepless regulation and the pilot pressure.

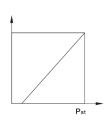
Adjust the proportion of the applied lead pressure.

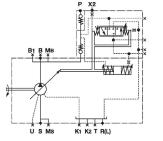
Option: pilot pressure characteristic curve, HD1, HD3, HD2;

pressure control HD.B, remote control HD.GB:

Power control DH1P;

Electrical lead pressure control HD1T;





2. The code of control section and technical parameter

• Hydraulic control HD

Outline

HD Hydraulic control of displacement dependent on pilot pressure signal. The displacement is proportional to the pilot pressure. The mechanical pivot angle limit setting range is 50%--100%Vgmax.

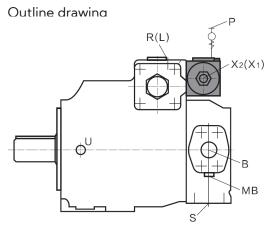
The ordering code number as following form



Pilot pressure characteristic	40	71	125	180	250	355	500		HD	
1-4.5 Mpa	Δ	Δ	Δ	Δ	Δ	Δ	Δ	1		
1-2.8 Mpa	Δ	Δ	Δ	Δ	Δ	Δ	Δ	2	-	
0.55-1.9 Mpa	Δ	Δ	Δ	Δ	Δ	Δ	Δ	3	•	
	Clo	sed lo	op pres	sure co	ntrol				-	
Control at A port	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Α	-	
Control at B port	Δ	Δ	Δ	Δ	Δ	Δ	Δ	В	- -	

Without pressure control/need not fill the code

Note: $\sqrt{\text{available}}$; Δ in preparation



Technical parameter

recrimed parameter								
Size		40	71	125	180	250	355	500
Control moving distance	mm	14.2	17.3	20.7	20.7	25.9	25.9	32.6
Control area	cm²	3.9	6.4	9	9	14.4	14.4	18.8
Control volume	cm³	5.5	11	18.7	18.7	37.3	37.3	61.4
Min.control pressure	Мра	3	3	5	5	5	5	5
Control time 20Mpa pressure	S	0.1	0.1	0.1	0.1	0.2	0.2	0.8

Hydraulic displacement control HD

Outline

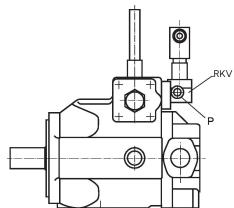
In the EO electric control work, the pump flow could set by proportion direction valve. Mean while, pump's current flow through inductance type position transducer feedback signal. This pump could reset the cylinder's zero position by the spring controls in the situation of normal pressure.

Do not reset at high-pressured work. Simultaneously, in order to reduce controls cylinder's loss flow, all size of hydraulic pressure fluid cylinder cavity is sealed.

The ordering code number as following form

J						40	71	125	180	250	355	500	
	EO	1				Δ	Δ	Δ	Δ	Δ	Δ	Δ	EO1
11 1 1	EO	1		Е		Δ	Δ	Δ	Δ	Δ	Δ	Δ	EO1E
Hydraulic control with	EO	1			K	Δ	Δ	Δ	Δ	Δ	Δ	Δ	EO1K
proportion	EO		2			Δ	Δ	Δ	Δ	Δ	Δ	Δ	EO2
valve	EO		2	Е		Δ	Δ	Δ	Δ	Δ	Δ	Δ	EO2E
	EO		2		K	Δ	Δ	Δ	Δ	Δ	Δ	Δ	EO2K
Max.setting pressure 10Mpa Bypass valve													
Max.setting pressure 35Mpa Withour valve													

Outline drawing



Specification of oil ports:

P Pressure port: M22 x 1.5 deep 16 RKV Case drain port: M22 x 1.5 deep 16



Technical parameter

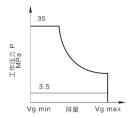
Size		40	71	125	180	250	355	500
Control cylinder's moving distance	mm	14.2	17.3	20.7	20.7	25.9	25.9	32.8
Control cylinder area	cm²	8.1	12.6	18.1	16.1	28.3	28.3	38.2
Control volume	cm³	11.4	21.5	37.5	37.5	37.3	73.2	124.5
Min.control pressure	Мра	10	10	10	12.5	12.5	12.5	15
Max.control pressure	Мра	31.5	31.5	31.5	31.5	31.5	31.5	31.5
Control time	S	0.1	0.12	0.2	0.2	0.25	0.25	0.3

Power control LR

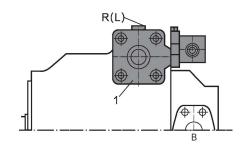
Outline

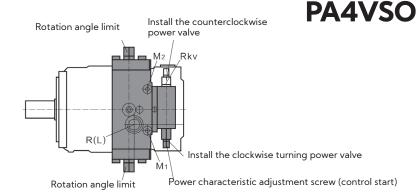
At the very beginning, the control scope could use the mechanical way to set, the setting value scope could use the spring and screw to adjust. When the pressure decreases, we could adjust spring and enter its starting position, the setting range of preset value:3.5Mpa--35Mpa. The smallest and the biggest angle of rotation's limit can use the mechnical way, adjustment to Vgmax 50%.

Characteristic curv



Outline drawing





The ordering code number as following form

Used for hydraulic drives in open loop circuits with the hyperbolic curve characteristic power adjuster, basic setting value Vgmax

Power regulation	40	71	125	180	250	355	500		LR	
The machinery adjust	$\sqrt{}$	$\sqrt{}$	\checkmark	$\sqrt{}$	$\sqrt{}$	Δ	Δ	2		
Remote hydraulic control	Δ	Δ	Δ	Δ	Δ	Δ	Δ	3		
		Pre	ssure co	ontrol						
With pressure control	√	\checkmark	\checkmark	\checkmark	\checkmark	Δ	Δ	D		'
With pressure control, remote hydraulic control	\checkmark	\checkmark	√	\checkmark	\checkmark	Δ	Δ	G		
Witho	out pre	ssure c	ontrol/ı	need n	ot fill th	e code				
		Flow	contro	ol, limit						
With mechanical traveling schedule limit	Δ	Δ	Δ	Δ	Δ	Δ	Δ	М		

Without flow control, limit, need not fill the code

Note: $\sqrt{\text{available}}$; Δ in preparation



Used for hydraulic drives in open, semi-close and close loop circuits with the hyperbolic curve characteristic power adjuster, basic setting value Vgmax depend on control pressure

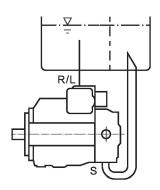
Power regulation	40	71	125	180	250	355	500		LR	N
The machin- ery adjust	Δ	Δ	Δ	Δ	Δ	Δ	Δ	2 -		
Remote hy- draulic control	Δ	Δ	Δ	Δ	Δ	Δ	Δ	3	_	
		Pr	essure (control						
With pressure control	Δ	Δ	Δ	Δ	Δ	Δ	Δ	D.		
With pressure control, re- mote hydrau- lic control	Δ	Δ	Δ	Δ	Δ	Δ	Δ	G	-	

Without flow control, limit, need not fill the code

Note: $\sqrt{\text{available}}$; Δ in preparation

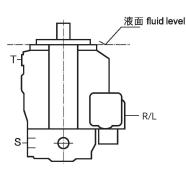
The hydraulic pump installed outside a tank If the pump installed below the tank, drain pipe and port S must be piped, as right diagram.

If the pump installed above the tank, drain pipe and port S must be piped, refer.



Vertical installation

The hydraulic pump installed within a tank If the minimum fluid level is level with of above the pump, mounting flange case drain ports T, S and port R/L are open, as right diagram.

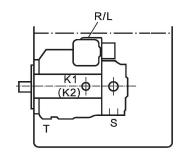


* Installation Postion

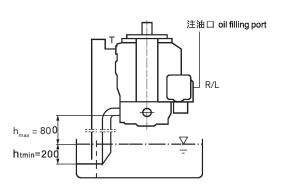
Horizontal installation

The hydraulic pump installed within a tank If the minimum fluid level is level above the top of pump, case drain ports and port S are open, as right diagram.

If the minimum fluid level falls the top of pump, case drain ports and port S must be piped, as following diagram.



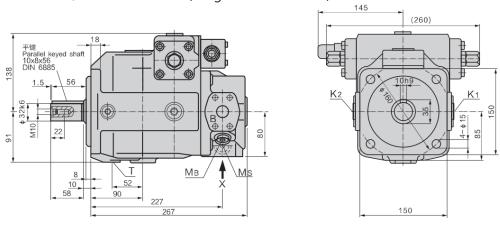
If the minimum fluid level fall below the pump mounting flange, case drain ports T, S and port P/L must be piped, as right diagram.

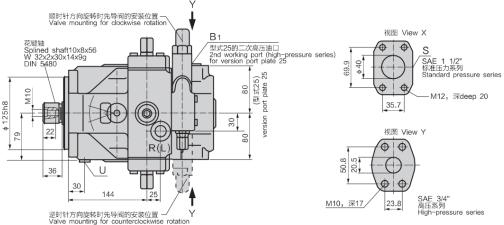




* Dimentions & Size

Dimensions, Size PA4VSO-40 (Diagram: DR Variable)

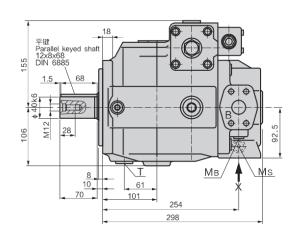


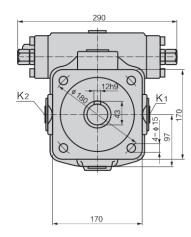


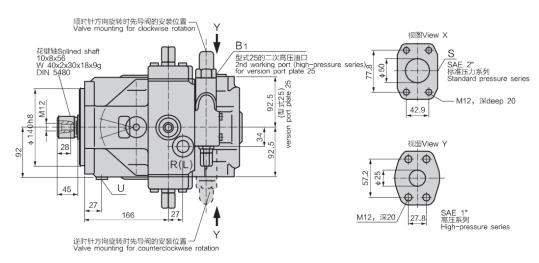
В	Pressure port	ø20.5
B1	Auxiliary pressure port When the working port type is 25, B1 port correspondingviewed on Y direction.	M22 x 1.5 deep 16
S	Suction port	ø40
Т	Case drain port	M22 x 1.5 deep 16
R(L)	R(L) Fluid fill and air bleed port	M22 x 1.5
$M_B M_S$	Test port	M14 x 1.5 deep 12
K ₁ K ₂	Flushing port	M22 x 1.5 deep 14
U	Bearing flushing port	M14 x 1.5 deep 12 plugged

* Dimentions & Size

Dimensions, Size PA4VSO-71 (Diagram: DR Variable)





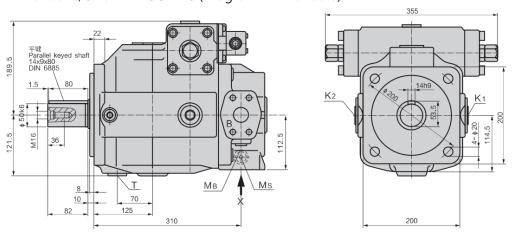


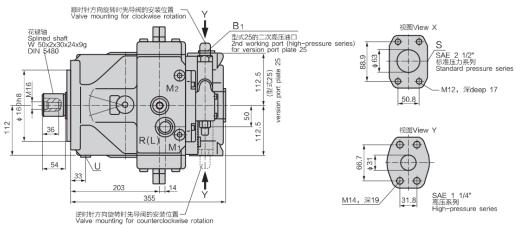
B1 Auxiliary pressure port M27 x 2 d	
When the working port type is 25, B1 port correspondingviewed on Y direction.	leep 16
S Suction port ø50	
T Case drain port M27 x 2 d	leep 16
R(L) R(L) Fluid fill and air bleed port $M27 \times 2$	
$K_1 K_2$ Flushing port M27 x 2 d	leep 16



* Dimentions & Size

Dimensions, Size PA4VSO-125 (Diagram: DR Variable)

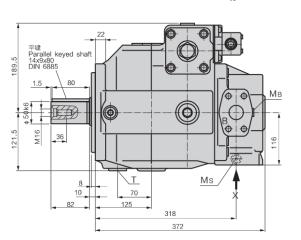


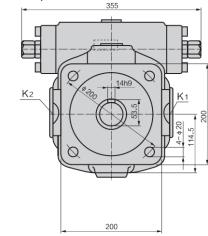


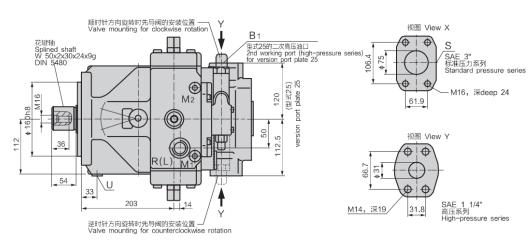
В	Pressure port	ø31
B1	Auxiliary pressure port When the working port type is 25, B1 port correspondingviewed on Y direction.	M32 x 2 deep 18
S	Suction port	ø63
Т	Case drain port	M33 x 2 deep 18
R(L)	R(L) Fluid fill and air bleed port	M33 x 2
$M_B M_S$	Test port	M14 x 1.5 deep 12
K ₁ K ₂	Flushing port	M33 x 2 deep 18
U	Bearing flushing port	M14 x 1.5 deep 12 plugged

* Dimentions & Size

Dimensions, Size PA4VSO-180 (Diagram: DR Variable)





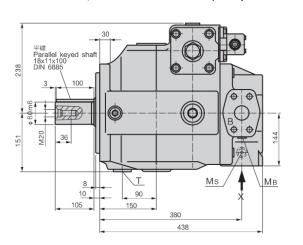


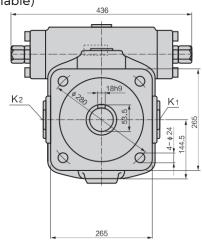
В	Pressure port	ø31
B1	Auxiliary pressure port When the working port type is 25, B1 port correspondingviewed on Y direction.	M33 x 2 deep 18
S	Suction port	ø75
Т	Case drain port	M33 x 2 deep 18
R(L)	R(L) Fluid fill and air bleed port	M33 x 2
$M_B M_S$	Test port	M14 x 1.5 deep 12
K ₁ K ₂	Flushing port	M33 x 2 deep 18
U	Bearing flushing port	M14 x 1.5 deep 12 plugged

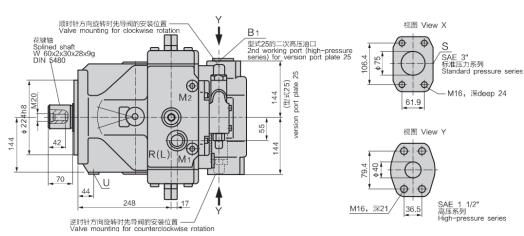


* Dimentions & Size

Dimensions, Size PA4VSO-250 (Diagram: DR Variable)



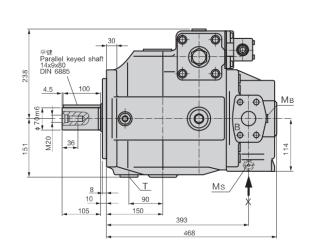


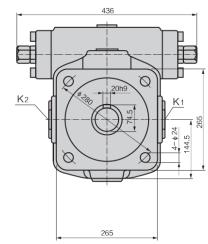


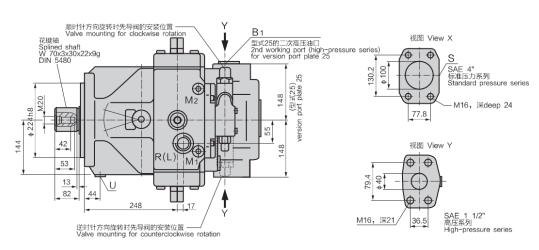
В	Pressure port	ø40
B1	Auxiliary pressure port When the working port type is 25, B1 port correspondingviewed on Y direction.	M33 x 2 deep 18
S	Suction port	ø75
Т	Case drain port	M42 x 2 deep 18
R(L)	R(L) Fluid fill and air bleed port	M42 x 2
M _B M _S	Test port	M14 x 1.5 deep 12
K ₁ K ₂	Flushing port	M42 x 2 deep 18
U	Bearing flushing port	M14 x 1.5 deep 12 plugged

* Dimentions & Size

Dimensions, Size PA4VSO-355 (Diagram: DR Variable)





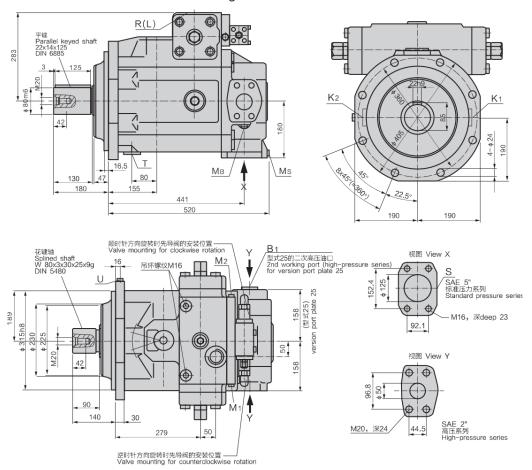


В	SAE 1 1/2" M42 x 2	
B1	4" M42 x 2 M14 x 1.5 M24 x 2	M18 x 1.5 M18 x 1.5
S	Suction port	ø100



* Dimentions & Size

Dimensions, Size PA4VSO-500 (Diagram: DR Variable)



В	Pressure port	SAE2n"
B1	Auxiliary pressure port When the working port type is 25, B1 port correspondingviewed on Y direction.	M48 x 2 deep 22
S	Suction port	SAE5n"
Т	Case drain port	M48 x 2 deep 22
R(L)	R(L) Fluid fill and air bleed port	M48 x 2
$M_B M_S$	Test port	M18 x 2 deep 12
K ₁ K ₂	Flushing port	M48 x 2 deep 12
U	Bearing flushing port	M18 x 1.5 deep 12

